MUTHAYAMMAL ENGINEERING COLLEGE
(An Autonomous Institution)
(Approved by AICTE, New Delhi, Accredited by NAAC \& Affiliated to Anna University)
Rasipuram - 637 408, Namakkal Dist., Tamil Nadu
Must Know Concepts (MKC)

## RA

| Subject |  | 19RAC10 - Metrology and Measurement |  |  |
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| $\begin{gathered} \text { S.N } \\ 0 \\ \hline \end{gathered}$ | Term | Notation (Symbol) | Concept/Definition/Meaning/Units/Equation/ Expression | Units |
| Unit-I Basics of Metrology |  |  |  |  |
| 1 | Metrology |  | Science of Measurement |  |
| 2 | Metrology types |  | Fundamental Metrology, Industrial Metrology, and Legal Metrology. |  |
| 3 | Uses of Metrology |  | Measurements are used in manufacturing and other processes |  |
| 4 | Units |  | Meter (m), Kilogram (kg), Second (S), Kelvin (K), Ampere (A), Mole (mol), and Candela (cd) |  |
| 5 | Measurement |  | Assigning a number to a characteristic of an Object |  |
| 6 | Measurement System |  | It is used to compare the physical quantity with the Standard value. <br> 1. MKS System 2. CGS System 3. FPS System 4. SI System |  |
| 7 | Measuring tools |  | 1. Vernier Caliper <br> 2. Thread gauge <br> 3. Feeler gauge <br> 4. Micrometer <br> 5. Dial Indicator <br> 6. Torque Wrench <br> 7. Torque Angle Gauge |  |
| 8 | Need of Measurements |  | Measurement is needed to find <br> 1. True dimensions of a part <br> 2. Physical Parameters <br> 3. Performance of a system |  |
| 9 | Methods of Measurements |  | 1. Direct Method <br> 2. Indirect Method <br> 3. Absolute Method <br> 4. Comparison method <br> 5. Transposition Method <br> 6. Substitution Method <br> 7. Coincidence Method |  |
| 10 | Elements of Measurements |  | 1. Primary sensing elements <br> 2. Variable Conversion Element <br> 3. Variable Manipulation Element <br> 4. Data Transmission Element <br> 5. Data Presentation Element |  |


| 11 | Elements of Metrology | 1. Standard <br> 2. Work piece <br> 3. Instrument <br> 4. Person <br> 5. Environment |  |
| :---: | :---: | :---: | :---: |
| 12 | Standard | A known accurate measure of physical quantity is termed as Standard. |  |
| 13 | Instrument | Measuring Devices that transform the measured quantity into an indication |  |
| 14 | Environment | The surroundings or conditions in which an instrument operates |  |
| 15 | Accuracy | The degree to which the result of a measurement confirms to the correct value |  |
| 16 | Precision | The closeness of two or more measurements |  |
| 17 | Repeatability | Closeness of the agreement between the results of successive measurements of the same measure |  |
| 18 | Reproducibility | The extent to which consistent results are obtained when an experiment is repeated. |  |
| 19 | Calibration | Evaluating and adjusting the precision and accuracy of measurement equipment |  |
| 20 | Calibration Types | 1. Transducer Calibration <br> 2. Data system calibration <br> 3. Physical end-to-end calibration |  |
| 21 | Errors | The difference between a measured value of a quantity and its true value |  |
| 22 | Types of Error | 1. Systematic Error <br> 2. Random Error <br> 3. Gross Error |  |
| 23 | Types of Standard | 1. Line standard <br> 2. End standard <br> 3. Wavelength standard |  |
| 24 | Line standard | Distance between two parallel lines or two surfaces |  |
| 25 | End standard | Distance between two flat parallel faces |  |


| Unit-II Linear and Angular Measurements |  |  |  |
| :---: | :---: | :---: | :---: |
| 1 | Linear <br> Measuring | Instruments are designed to measure the distance between two surfaces or points like Vernier Caliper, Micrometer |  |
| 2 | Linear <br> Measurement | Measurements of length, diameter, height and thickness |  |
| 3 | Types of Linear <br> Measuring <br> Instruments | Vernier Caliper <br> Micrometer <br> Vernier Depth Gauge Vernier Height Gauge Comparator |  |
| 4 | Vernier Caliper | It is a visual aid to take an accurate measurement reading between two graduation markings on a linear scale by using mechanical interpolation |  |
| 5 | Types of Vernier Caliper | 1. A Type Vernier Caliper <br> 2. B Type Vernier Caliper <br> 3. C Type Vernier Caliper |  |
| 6 | Parts of Vernier Caliper | 1. Main Scale <br> 2. Vernier Scale <br> 3. External Measuring faces <br> 4. Internal Measuring Faces <br> 5. Depth Measuring Balance |  |
| 7 | Least Count of Vernier | 0.02 mm |  |
| 8 | Parts of Vernier Height Gauge | 1. Base <br> 2. Beam <br> 3. Measuring Jaw <br> 4. Scriber <br> 5. Slider |  |
| 9 | Least Count of Micrometer | 0.01 mm |  |
| 10 | Micrometer | It is a device incorporating a calibrated screw widely used for accurate measurement of components |  |
| 11 | Classification of Micrometer | 1. Outside Micrometer <br> 2. Inside Micrometer |  |
| 12 | Criteria for selecting materials for Slip Gauges | 1. High Hardness <br> 2. Temperature Stability <br> 3. Corrosion Resistance <br> 4. High Quality Finish |  |
| 13 | Angular <br> Measurement | Includes the measurement of angles or tapers |  |
| 14 | Gauge Materials | Basic metals, Glass, Plastics, Aluminum, Brass, Steel, Polycarbonate and Polypropylene |  |
| 15 | Purpose of gauge | A gauge is a device used for Inspection Purposes |  |
| 16 | Limit gauge | Method of checking dimensions using fixed gauge to determine whether a given |  |


|  |  | component lies within its limit |  |  |
| :--- | :--- | :--- | :--- | :--- |
| 17 | Advantages of <br> Limit Gauges |  | Quicker Inspection Method used in Mass <br> Production |  |
| 18 | Types of Gauges |  | 1. GO Gauge <br> 2. NOGO Gauge |  |
| 19 | Interchangabilit <br> y |  | Ability of components to assemble to form a <br> final Product |  |
| 20 | Fit | Degree of tightness or looseness between two <br> mating parts |  |  |
| 21 | Sine bar | Sine bar is used in conjunction with slip gauge <br> for precise angular measurement |  |  |
| 22 | Angle Dekkor |  | Optical device that uses the principle of Auto <br> collimation for measuring small angles |  |
| 23 | Bevel Protractor |  | It is a graduated circular protractor with one <br> pivoted arm to measure angles |  |
| 24 | Clinometers | Clinometers is an instrument used for <br> measuring angles of slope (or tilt) |  |  |
| 25 | Autocollimator | Autocollimator is an optical instrument for <br> non-contact measurement of angles |  |  |
| 10 | Unit-III Advances in Metrology |  |  |  |


| 11 | Advantages of Column Type CMM | 1. Quicker Inspection <br> 2. Accurate Measurements <br> 3. Easier to Position <br> 4. More Accurate <br> 5. No need to use GO/NOGO Gauges |  |
| :---: | :---: | :---: | :---: |
| 12 | Types of Accuracy used for CMM | 1. Geometry accuracies <br> 2. Total measuring accuracies <br> 3. Volumetric length measuring accuracies <br> 4. Environmental effects |  |
| 13 | Causes of Errors <br> in CMM | 1. Table of CMM may not have perfect geometric form. <br> 2. The probes may have a degree of run out. <br> 3. Probes should be minimum and rigid |  |
| 14 | Laser <br> Micrometer | Laser micrometers are the type that uses an encoder to detect the distance and displays the result on a digital screen. |  |
| 15 | Various <br> Geometrical <br> Checks in <br> Machine Tools | 1. Straightness <br> 2. Flatness <br> 3. Parallelism, equidistance and coincidence <br> 4. Rotations |  |
| 16 | Applications of Laser in Machine Tool Metrology | 1. Aircraft production, shipbuilding to check for limits and fits <br> 2. Testing of flatness of machined surfaces |  |
| 17 | Axial slip of Machine Tool | Machine tools are very sensitive to impact or shock, even heavy casting standards are not always solid and rigid enough to withstand stresses due to falling during transportation |  |
| 18 | Methods of Dimensional Measurements using Laser | 1. Laser telemetric system <br> 2. Laser Triangulation sensors <br> 3. Two frequency laser interference |  |
| 19 | Laser <br> Interferometer Components | 1. Two frequency laser source <br> 2. Optical elements <br> 3. Laser heads measurement receiver <br> 4. Measurement display |  |
| 20 | Types of Laser Interferometer | 1. AC Interferometer <br> 2. DC Interferometer |  |
| 21 | Types of AC Laser Interferometer | 1. Standard Interferometer <br> 2. Single Beam Interferometer |  |
| 22 | Other Types of Interferometer | 1. Michelson Interferometer <br> 2. Twyman green specialization of Michelson Interferometer <br> 3. Dual frequency laser Interferometer |  |
| 23 | Machine vision | Machine vision is the ability of a computer to employ one or more video cameras, analog-todigital conversion (ADC) and digital signal processing (DSP). The resulting data goes to a |  |


|  |  | computer or robot controller. |  |
| :---: | :---: | :---: | :---: |
| 24 | Various stages of Machine vision | 1. Image Formation <br> 2. Image Processing <br> 3. Image Analysis <br> 4. Image Interpretation |  |
| 25 | Applications of Machine vision | 1. Measurements of Dimensions and Tolerance <br> 2. Guidance and Control <br> 3. Identification of Surface Defects <br> 4. Flatness Measurement <br> 5. Inspection of Printed Circuit Boards (PCB) |  |
| Unit-IV Form Measurement |  |  |  |
| 1 | Straightness | Condition where an element of a surface or an edge is in a straight line |  |
| 2 | Straight edge | Measuring tool which consists of length on steel of narrow and deep section |  |
| 3 | Screw thread | Helical ridge produced by forming a continuous helical groove of a uniform section on the external or internal surface of a cylinder |  |
| 4 | Types of Thread | 1. External Threads <br> 2. Internal Threads |  |
| 5 | Flank | Surface between crest and root |  |
| 6 | Pitch | Distance measured parallel to the axis from a point on a thread to the corresponding point |  |
| 7 | Types of Pitch Errors | 1. Progressive error <br> 2. Drunken error <br> 3. Periodic error <br> 4. Irregular errors |  |
| 8 | Wire Methods | 1. One wire method <br> 2. Two wire method <br> 3. Three wire method |  |
| 9 | Instruments for Measuring Pitch Diameter | 1. Pitch measuring machine <br> 2. Tool maker <br> 3. Screw pitch gauge |  |
| 10 | Drunken Thread | The advance of the helix is irregular in one complete revolution of thread |  |
| 11 | Velocity ratio | To calculate the speed of the driven gear multiply the speed of the driver gear by the velocity ratio. |  |
| 12 | Types of Gear | 1. Spur Gear <br> 2. Helical Gear <br> 3. Gear Rack <br> 4. Internal Gear |  |
| 13 | Circular Pitch | The distance along the pitch circle or pitch line between corresponding profiles of adjacent teeth |  |

\(\left.$$
\begin{array}{|l|l|l|l|l|}\hline 14 & \text { Force ratio } & & \begin{array}{l}\text { Ratio of the output force (load) of a machine to } \\
\text { the input force (effort) }\end{array} & \\
\hline 15 & \text { Runout } & \begin{array}{l}\text { Runout is an inaccuracy of rotating mechanical } \\
\text { systems, specifically that the tool or shaft does } \\
\text { not rotate exactly in line with the main axis }\end{array} & \\
\hline 16 & \text { Roundness ratio } & & \begin{array}{l}\text { The ratio of the polar diameter to the } \\
\text { equatorial diameter of a sphere }\end{array} & \\
\hline 17 & \text { Addendum } & & \begin{array}{l}\text { The distance between the reference line and } \\
\text { the tooth tip. }\end{array} & \\
\hline 18 & \text { Dedendum } & \begin{array}{l}\text { The distance between the reference line and } \\
\text { the tooth root }\end{array} & \\
\hline 19 & \text { Pitch point } & & \begin{array}{l}\text { The point of contact of the pitch lines of two } \\
\text { gears or of a rack and pinion when in mesh. }\end{array} & \\
\hline 20 & \begin{array}{l}\text { Diametrical } \\
\text { pitch }\end{array} & \begin{array}{l}\text { The number of teeth divided by the pitch } \\
\text { diameter. }\end{array} & \\
\hline 21 & \begin{array}{l}\text { Types of Thread Plug Screw Gauge } \\
\text { Gauge }\end{array}
$$ \& Fl. Ring Screw Gauge <br>

3. Caliper Gauges\end{array}\right]\)| It is defined as minimum distance between two |
| :--- |
| planes. |


|  |  | 4. Metal foil strain gauge <br> 5. Piezo -resistive strain gauge |  |
| :---: | :---: | :---: | :---: |
| 9 | Types of Flow Meter | 1. Venturimeter <br> 2. Orificemeter <br> 3. Rotometer <br> 4. Pitot tube |  |
| 10 | Thermistor | Defined as a type of resistor whose electrical resistance varies with changes in temperature. |  |
| 11 | Types of Thermistor | 1. Bead type <br> 2. Water type <br> 3. Rod type <br> 4. Washer type |  |
| 12 | Thermopile | When thermocouples are connected in series it is called as thermopiles |  |
| 13 | Thermocouple Materials | 1. Chrome <br> 2. Alumel <br> 3. Copper <br> 4. Iron <br> 5. Platinum <br> 6. Rhenium |  |
| 14 | Thermocouple | A Thermocouple is a sensor used to measure temperature. Thermocouples consist of two wire legs made from different metals. |  |
| 15 | Laws of thermo couple | 1. Law of intermediate metals <br> 2. Law of intermediate temperature |  |
| 16 | Pyrometer | Type of remote-sensing thermometer used to measure the temperature of a surface. |  |
| 17 | Types of Pyrometers | 1. Total Radiation Pyrometer <br> 2. Optical Radiation Pyrometer |  |
| 18 | Materials for Bimetallic strips | 1. Invar <br> 2. Brass <br> 3. Nickel - iron alloy |  |
| 19 | Force | Mechanical force is a force that needs a physical contact between the system which applies the force and the system on which the force is applied. |  |
| 20 | Types of Forces | 1. Applied Force <br> 2. Gravitational Force <br> 3. Normal Force <br> 4. Frictional Force <br> 5. Air Resistance Force <br> 6. Tension Force. <br> 7. Spring Force |  |
| 21 | Force measurement methods | 1. Direct Comparison <br> 2. Indirect Comparison |  |
| 22 | Devices used for Measuring Force | 1. Scale and Balance <br> 2. Elastic Force meter Proving Ring <br> 3. Load Cell |  |


| 23 | Torque |  | Turning or twisting action of the force. The SI unit of torque is Nm |  |
| :---: | :---: | :---: | :---: | :---: |
| 24 | Torque <br> Measuring <br> Instruments |  | 1. Mechanical Torsion Meter <br> 2. Optical Torsion Meter <br> 3. Electrical Torsion Meter <br> 4. Strain Gauge Torsion Meter |  |
| 25 | Types of Dynamometers |  | Absorption Dynamometers Driving Dynamometers Transmission Dynamometers |  |
| Aptitude Questions and Answers |  |  |  |  |
| S.No | Term | Notation (Symbol) | Concept/Definition/Meaning/Units/Equation /Expression | Units |
| 1 | A person crosses a 600 m long street in 5 minutes. What is his speed in km per hour? |  | A. 3.6 <br> B. 7.2 <br> C. 8.4 <br> D. 10 <br> Explanation: <br> Speed $=600 / 5 \times 60 \mathrm{~m} / \mathrm{sec} .=2 \mathrm{~m} / \mathrm{sec} .=2 \mathrm{x}$ <br> $18 / 5 \mathrm{~km} / \mathrm{hr}=7.2 \mathrm{~km} / \mathrm{hr}$ |  |
| 2 | An express train travelled at an average speed of $100 \mathrm{~km} / \mathrm{hr}$, stopping for 3 minutes after every 75 km . How long did it take to reach its destination 600 km from the starting point? |  | A. 6 hrs 27 min <br> B. 6 hrs 24 min <br> C. 6 hrs 21 min <br> D. 6 hrs 30 min <br> Explanation: <br> Time taken to cover $600 \mathrm{~km}=(600 / 100) \mathrm{hrs}=6$ hrs. <br> Number of stoppages $=600 / 75-1=7$. <br> Total Time of stoppages $=(3 \times 7) \mathrm{min}=21 \mathrm{~min}$. Hence, total time taken=6 hrs 21 min . |  |
| 3 | The ratio between the length and the breadth of a rectangular park is 3: 2. If a man cycling along the boundary of the park at the speed of 12 $\mathrm{km} / \mathrm{hr}$ completes one round in 8 minutes, then the area of the park (in sq. m) is |  | A. 15360 <br> B. 153600 <br> C. 30720 <br> D. 307200 <br> Explanation: <br> Perimeter $=$ Distance covered in 8 min . $=12000 \times 8 \mathrm{~m}=1600 \mathrm{~m}$. <br> Let length $=3 \mathrm{x}$ metres and breadth $=2 \mathrm{x}$ metres. <br> Then, $2(3 x+2 x)=1600$ or $x=160$. <br> Length $=480 \mathrm{~m}$ and Breadth $=320 \mathrm{~m}$. <br> Area $=(480 \times 320) \mathrm{m}^{2}=153600 \mathrm{~m}^{2}$. |  |


| 4 | If a cost price of a pencil box is Rs. 67 and selling price is Rs.70.Is there is profit or loss? | A. Rs. 2 <br> B. Rs. 3 <br> C. Rs.4wrong <br> D. RS. 5 <br> Explanation: <br> C.P = RS. 67 , S.P = Rs. 70 As, S.P >C.P it means profit .profit $=$ S.P-C. $\cdot \mathrm{P}=$ Rs .3 |  |
| :---: | :---: | :---: | :---: |
| 5 | A and B started a business by investing <br> Rs.4000/- and Rs.5000/respectively. <br> Find the A's share out of a total profit of Rs.1800: | A. Rs.1000/- <br> B. Rs.1800/- <br> C. Rs.800/- <br> D. Rs.400/- <br> Explanation: <br> A = Rs.4000/- <br> B = Rs.5000/- <br> A share 4 parts \& B share 5 parts <br> Total 9 parts -----> Rs.1800/- <br> ----> 1 part -------> Rs.200/- <br> A share $=4$ parts -----> Rs.800/- |  |
| 6 | Two pipes can fill the cistern in 10 hr and 12 hr respectively, while the third empty it in 20hr. If all pipes are opened simultaneously, then the cistern will be filled in | A. 7.5 hr <br> B. 8 hr <br> C. 8.5 hr <br> D. 10 hr <br> Explanation: <br> Work done by all the tanks working together in 1 hour. $110+112-120=215$ <br> Hence, a tank will be filled in $152=7.5$ hour |  |
| 7 | A train running at the speed of $60 \quad \mathrm{~km} / \mathrm{hr}$ crosses a pole in 9 seconds. What is the length of the train? | A. 120 metres <br> B. 180 meters <br> C. 150 meters <br> D. 324 meters <br> Explanation: <br> Speed $=60 \times 5 / 18 \mathrm{~m} / \mathrm{sec}=50 / 3 \mathrm{~m} / \mathrm{sec}$. <br> Length of the train $=($ Speed $x$ Time $)$. <br> Length of the train $=50 / 3 \mathrm{x} 9 \mathrm{~m}=150 \mathrm{~m}$. |  |
| 8 | A boat can  <br> travel with a <br> speed of 13 <br> $\mathrm{~km} / \mathrm{hr}$ in still <br> water. If the <br> speed of the <br> stream is 4 <br> $\mathrm{~km} / \mathrm{hr}$ find the <br> time taken by <br> the boat to   | A. 2 hours <br> B. 3 hours <br> C. 4 hours <br> D. 5 hours <br> Explanation: <br> Speed downstream $=(13+4) \mathrm{km} / \mathrm{hr}=$ $17 \mathrm{~km} / \mathrm{hr}$. <br> Time taken to travel 68 km downstream $=68 / 17 \mathrm{hrs}=4 \mathrm{hrs}$. |  |



|  | interchanging the two digits is 36, what is the difference between two numbers | Explanation: <br> Let the ten digit be x , unit digit is y . Then $(10 x+y)-(10 y+x)=36$ $\begin{aligned} & \Rightarrow 9 x-9 y=36 \\ & \Rightarrow x-y=4 . \end{aligned}$ |  |
| :---: | :---: | :---: | :---: |
| 15 | Find the odd man out. $1,3,9$, 12, 19, 29 | A. 12 <br> B. 9 <br> C. 1 <br> D. 3 <br> Explanation : <br> 12 is an even number. All other given numbers are odd |  |
| 16 | Find the odd man out. Shakespeare | A. Romeo <br> B. Hamlet <br> C. Novel <br> D. Play <br> Explanation: <br> Shakespeare was involved in all three forms of literature except NOVEL. Thus, option 3 is correct. |  |
| 17 | Find the <br> Missing  <br> Number 2, <br> 12, 60, <br> 10, 42, <br> 56,  | A. 60 <br> B. 64 <br> C. 72 <br> D. 70 <br> Explanation: <br> Pattern is $1 * 2,2 * 3,3 * 4,4 * 5,5 * 6,6 * 7$, 7 * 8 <br> i.e) $8 * 9=72$ |  |
| 18 | In 100 m race, A covers the distance in 36 seconds and B in 45 seconds. In this race A beats B by: | A. 20m <br> B. 25 m <br> C. 22.5 m <br> D. 9 m <br> Explanation: <br> Distance covered by B in $9 \mathrm{sec} .=(100 / 45)^{*} 9 \mathrm{~m}$ $=20 \mathrm{~m}$ <br> A beats B by 20 meters. |  |
| 19 | Raju age after 15 years will be 5 times his age 5 years back, What is the present age of Raju | A. 15 <br> B. 14 <br> C. 10 <br> D. 8 <br> Explanation: <br> Clearly, $x+15=5(x-5)$ $\Leftrightarrow 4 x=40 \Rightarrow x=10$ |  |
| 20 | Ten years ago, P was half of Q's age. If the ratio of their present ages is 3:4, what will be the total of | A. 45 <br> B. 40 <br> C. 35 <br> D. 30 <br> Explanation: <br> Let the present age of P and Q be 3 x and 4 x respectively. |  |


|  | $\begin{aligned} & \hline \text { their } \quad \text { present } \\ & \text { ages? } \end{aligned}$ | Ten years ago, P was half of Q 's age $\begin{aligned} & (3 x-10)=1 / 2(4 x-10) ? 6 x-20=4 x-10=> \\ & 2 x=10=>x=5 \end{aligned}$ <br> Total of their present ages $=3 x+4 x=7 x=7 \times 5=35$ |  |
| :---: | :---: | :---: | :---: |
| 21 | Solve the equation $x+34=82$ | A. 58 <br> B. 48 <br> C. 55 <br> D. 60 <br> Explanation: $x=82-34=48$ |  |
| 22 | $\text { Find } c \text {, if } 5 \mathrm{c}-2$ $=33$ | A. 7 <br> B. 9 <br> C. 11 <br> D. 13 <br> Explanation: <br> We add 2 to both sides and get $5 \mathrm{c}-2+2=33+2$, or $5 \mathrm{c}=35$. We divide both sides by 5 in order to get $\mathrm{c}=7$. |  |
| 23 | A fires 5 shots to B's 3 but A kills only once in 3 shots while B kills once in 2 shots. When B has missed 27 times, A has killed : | A. 30 birds <br> B. 60 birds <br> C. 72 birds <br> D. 90 birds <br> Explanation: <br> Let the no of shots be $x$. Then, <br> Shots fired by A $=(5 / 8) \mathrm{x}$ <br> Shots fired by B = $(3 / 8) \mathrm{x}$ <br> Killing shots by $\mathrm{A}=1 / 3$ of $(5 / 8) \mathrm{x}=(5 / 24) \mathrm{x}$ <br> Shots missed by B $=1 / 2$ of $(3 / 8) x=(3 / 16) x$ <br> (3/16) $x=27$ ? $x=144$ <br> Birds killed by $\mathrm{A}=(5 / 24) \mathrm{x}=(5 / 24) * 144=30$ |  |
| 24 | f $\sqrt{2 n}=64$, then the value of $n$ is: | A. 2 <br> B. 4 <br> C. 6 <br> D. 12 <br> Explanation: $\begin{aligned} & \sqrt{ } 2 \mathrm{n}=64=>2 \mathrm{n} / 2=64=26 \\ & \mathrm{n} / 2=6 ; \mathrm{n}=12 \end{aligned}$ |  |
| `25 | $\begin{aligned} & \text { Solve }(x+1) \\ & (x-3)=0 . \end{aligned}$ | A. $-\mathbf{1 , 3}$ <br> B. 2,3 <br> C. $-1,5$ <br> D. $-1,6$ <br> Explanation: $\begin{aligned} & (x+1)(x-3)=0 \\ & x+1=0, x-3=0 \\ & x=-1, x=3 \end{aligned}$ <br> That was quick! And my answer is: $\mathrm{x}=-1,3$ |  |
|  | Team Prepares | Dr.T.Yuvaraj, ASP/MECH <br> P.Ramesh, AP/MECH <br> S.Palanisamy, ASP / MECH |  |

