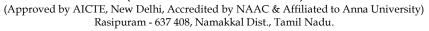


MUTHAYAMMAL ENGINEERING COLLEGE

(An Autonomous Institution)





MUST KNOW CONCEPTS

MKC

 $\mathbf{R}\mathbf{A}$

2021-22

Course Code & Course Name :

19RAC11 COMPUTER AIDED DESIGN & MANUFACTURING

Year/Sem/Sec :

S.N o.	Term	Notation (Symbol)	Concept / Definition / Meaning / Units / Equation / Expression	Units
0.	Unit-	, ,	MENTALS OF COMPUTER GRAPHICS	
1	Design Center palette		Standard toolbar	
2	F9 key		Snap on/off	
3	Dragging		Holding down the left-hand button of the mouse on an item can be moved to another point on screen.	
4	Tool tip		The tool name appearing in a rectangle when the cursor is placed on a tool icon	
5	Isometric drawing		A 2D (two-dimensional) pictorial view of the object.	
6	AutoCAD sheet set		A number of AutoCAD drawings saved in Paper Space format and held in a file	
7	Term UCS stands for		User Coordinate System.	
8	Phases Of Cad		Geometric modeling, analysis and optimization Design review and evaluation Documentation and drafting.	
9	Geometric Modeling		Geometric modeling involves the use of a CAD system to develop a mathematical description of the geometry of an object.	
10	Geometric Modeling Techniques		Two & Three dimensional modeling Wire frame modeling	
11	Merits of cad		High productivity and reduced lead time. Accuracy in design. Modifications in design relatively easy.	
12	Applications Cad Software package		Automated industries, Manufacturing companies Aerospace designs, Civil engineering plans,	
13	Cad Software Package		Auto CAD, CATIA, Iron CAD, Pro-E, Turbo CAD, Solid Edge	

	**** C		0. 1	
14	Wireframe Modeling merits		Simple to construct, Designer needs little training. It needs less memory space,	
15	B-rep		Consists of entering all boundary edge for all surfaces.	
16	CSG		Boolean combinations or primitives solids to build a part.	
17	Advantages Of Solid Modeling		It is complete and unambiguous. Automated applications like creating part program without much human involvement.	
18	Solid works		Its complete product development cycle starting from concept design to Detailed design	
19	CAM		Planning, Managing and Control	
20	Plan Drawings		Objects drawn from above or a birds-eye view and kept two dimensional.	
21	Wireframe		When drawing in plan view all drawings will be simple lines and lack any color	
22	Images created in this CAD class utilize points	74	Vector - Based	
23	Open GL		The fastest way to view rendered three dimensional shapes in full color	
24	3D objects		X,Y,Z Axis System	
25	Manager Design Tree		Part Subassembly Flexible Subassembly	
		Unit-I	I : GEOMETRIC MODELING	
26	BOM In Solid works		In Solid Works, BOM creates bill automatically and cut lists for downstream manufacturing and purchasing operation	
27	Roles of geometric modelling		Analytical curves, interpolates curves, approximate curves.	
28	Types of conic section		Hyperbola, elipse, parabola.	
29	Equ. of parabola		Y2=4ax	
30	Non-Parametric equation		X2+y2=r2	
31	NURBS		Non-uniform rational B-splines	
32	Types of surface		Plane, ruled, tabulated, surface of revolution, Bezier, B-spline, coons, fillet, offset	
33	C0		Tangent Could Have Sudden Change In Curvature.	
34	CSG		Constructive solid geometry	
35	Euler's operation		V-E+F=H+2(B-G)	
36	Product cycle		The process of managing the entire lifecycle of a product from starting.	

37	Product life		Concept, planning, marketing, design,	
	cycle of		Manufacture service.	
38	Concurrent engineering		Various tasks are handles at the same time, and not essentially in the standard order.	
	Computer		Graphical representation of objects in a	
39	graphics		computer.	
40	Rendering		The making of 2D model to 3D model by means of computer programs.	
41	Anti-aliasing		Process for better illustration with multiple color gradations during drawing a line.	
42	Clipping		It is the method of cutting a graphics display to neatly fit a predefined graphics region.	
43	Application of solid modeling	200	Engineering, entertainment industry, medical industry	
44	Geometry		It is the study of shape and spaces.	
45	Topology		Unchanged after twisting, stretching.	
46	PI		Primitive instancing	
47	SWP		Sweep Presentations	
48	SPRs		Spatial partitioning representations	
49	Solid modeling techniques		Sweeping, cell decomposition	
50	Fillet surface		It is a B-spline surface that blends two surface	
		Uı	nit-III : VISUAL REALISM	
51	Rep.of curves and surfaces		Generic form, parametric form.	
52	CAD tools		Solid works, PRO- E, CATIA, Vector works,	
53	Computer Aided Manufacturing	CAM	Use of software and computer-controlled machinery to automate a manufacturing process	
54	Computer Graphics		Is a core technology in digital photography, film, video games, cell phone	
55	Product life cycle		Product goes through from when it was first thought of until it finally is removed from the market	
56	4 Phases of the product life cycle		Introduction, Growth, Maturity, Decline	
57	Morphology design		Morphology means 'a study of form or structure	
58	Structure design		Structural design is the methodical investigation of the stability, strength and rigidity of structures	
59	Sequential product development		stage of the process before passing the new product to the next department	
60	Enforced- discipline approach		Discipline is the practice of making people obey rules or standards of behavior, and punishing them when they do not	

61	Concurrent		Method of designing and developing products, in	
	engineering		which the different stages run simultaneously	
62	Geometric		The modelling of realistic objects for computer	
	modeling		graphics and computer aided design	
63	Solid modeling		Principles for mathematical and computer modeling of three-dimensional solids.	
			A variety of technologies that make images and	
64	Stereoscopic		movies appear more lifelike in print, on the	
04	imaging		computer, in the cinema or on TV	
			Edges are not hidden by the faces of parts for a	
65	Hidden line	HLR	specified view and the display of parts in the	
	removal	TILLIC	projection of a model into a 2D plane	
			Separates visible faces from invisible faces of an	
66	Computing		object with respect to a given viewing direction	
	silhouettes		is called silhouette edges (or silhouettes).	
			Controls which edges of a 3D face are visible,	
67	Invisible face		allowing for accurate modeling of objects with	
			holes	
			A planar <i>face</i> is created that is similar to a region	
68	Visible face		object. When you shade or render the object,	
			planar faces are filled	
	Hidden line		Edges are not hidden by the faces of parts for a	
69	removal	HLR	specified view and the display of parts in the	
	algorithms		projection of a model into a 2D plane	
70	Area oriented		An object-oriented tool integration methodology	
	approach		that treats the tools as objects is presented	
			computer graphics, z-buffering, also known as	
71	Depth buffer		depth buffering, is the management of image	
			depth coordinates in 3D graphics	
72	A 1		Computer-graphics algorithms often take	
72	Area coherence		advantage of area coherence, image compression	
			being an example	
73	Scan line		It is an image-space method to identify visible surface. This method has a depth information for	
/3	Scan inte		only single scan-line	
	Texture		Application of images to three-dimensional	
74	mapping		graphics to enhance the realism of their surfaces.	
	штрыц		A key frame in animation and film making is a	
75	Key frame		drawing that defines the starting and ending	
			points of any smooth transition	
	1	Uni	t-IV: ASSEMBLY OF PARTS	
76	Assembly		Computer software systems to handle multiple	
76	modelling		files that represent components within a product.	
77	Constraints		It restricts an entity, project, or system from	
//	Constraints		achieving its potential with reference to its goal	
			Total permissible variation of a size. It is the	
78	Tolerance		difference between maximum limit and	
			minimum limit of size.	
79	Deviation		The action of departing from an established	
			course or accepted standard	

80	Fundamental deviation	 The minimum difference in size between a	
	deviation	component and the basic size The nominal size and the limits on the hole are	
81	Hole basis	maintained constant and the shaft limits are	
01	system		
	-	varied to obtain the required fit.	
0.2	Unilateral	A unilateral tolerance is a tolerance in which	
82	tolerance	 variation is permitted only in one direction from	
		the specified dimension	
0.2	E'.	When two parts are to be assembled the relation	
83	Fit	 resulting from the difference between their sizes	
		before assembly	
0.4	GI C'	For any hole and shaft assembly, if the upper	
84	Clearance fit	 limit size of the shaft is less than the lower limit	
		size of the hole then that type of fit	
		Is a fastening between two parts which is	
85	Interference fit	achieved by friction after the parts are pushed	
0.5	interiorence in	together, rather than by any other means of	
		fastening	
86	Transition fit	Transition fits are a compromise between	
	Transition it	clearance and interference fits	
		An algorithm for creating a hidden-line drawing	
87	Depth sorting	 of polygon data sets by drawing the polygons	
		from the most distant to the closest	
		Activities related to the study of potential	
88	Tolerance	 accumulated variation in mechanical parts and	
	analysis	assemblies.	
		Pixel Shading is a method used for rendering	
89	Tightness or	 advanced graphical features such as bump	
0)	looseness	mapping and shadows	
		sequence of numbers where each term after the	
	Geometric	first is found by multiplying the previous one by	
90	progression	 a fixed, non-zero number called the common	
	progression	ratio	
	Unilateral	tolerance in which variation is permitted only in	
91	tolerance	 one direction from the specified dimension	
-	tolerance	consist of the upper and lower limits of a	
92	Tolerance limits	particular environmental condition which allows	
72		 a certain species to survive	
		 hidden-surface determination algorithm is a	
		<u> </u>	
93	Hidden surface	 solution to the visibility problem, which was one of the first major problems in the field of 3D	
		of the first major problems in the field of 3D	
		computer graphics	
04	Donth Conting	An algorithm for creating a hidden-line drawing	
94	Depth Sorting	 of polygon data sets by drawing the polygons	
		from the most distant to the closest, in order.	
0.5	Depth buffer	pixel on the display screen, we keep a record of	
95	algorithm	 the depth of an object within the pixel that lies	
-		closest to the observer	
0.5	D 41 · ·	Also known as a shadow map, is a texture that	
96	Depth texture	 contains the data from the depth buffer for a	
		particular scene	

07	G1 1 ' '		Rendering in Unity is done with Materials,	
97	Shaders in unity		Shaders and Textures	
98	Material in		Shades are small scripts that contain the	
	unity		mathematical calculations and algorithm	
99	Depth testing		The defects are logged, are captured across all parameters, functional and non functional	
	Painter's		Is one of the simplest solutions to the visibility	
100	algorithm		problem in 3D computer graphics	
		Un	iit-V :CAD STANDARDS	
101	CAD Standards		Communication of design and Manufacturing	
101			data within engineering organization	
102	Database		Collection of data at a single location to be used	
	Management		by various people for different applications	
103	Computer graphics		It is used for processing image data received from the physical world.	
			Number of levels describing the level of support	
104	GKS		in terms of facilities	
105	PHIGS		Programmer's Hierarchical Interface for	
103	THOS		Graphics	
106	IGES		Initial Graphics Exchange Specification	
107	STEP		Standard for the Exchange of Product Model	
107	SILI		data	
100	Graphics		allow images to be moved from machine to	
108	Standards		machine, while languages let graphics programs be moved from machine to machine	
	Workstation		If the normalized device coordinates are	
109	Transformation		translated into device coordinates	
110	Core System		The standardization of graphic system	
111	D : :::		Pictures are considered to be constructed from a	
111	Primitives		number of basic building blocks	
112	Neutral Formats		IGES, STEP, DXF	
113	Layer of STEP		Application Layer, Logical Layer	
113			Physical Layer	
114	IGES File		Flag Section, Start Section, Global Section	
	Section		, ,	
115	Application Programming	API	Number of function	
113	Interface	711 1	Transcript of Indiction	
			Is a cross language, multi-platform Application	
116	OpenGL		Programming Interface (API) for rendering 2D	
			and 3D vector graphics	
117	Flag section		Used only with the compressed ASCII and	
	-		binary format Deals with the data structures and data format	
118	Physical Layer		for exchange file itself	
110	Application		Consist of information of various application	
119	Layer		areas	
120	Logical Layer		Provide a consistent, computer-independent	
	ı	ı		

			description of the data constructs that contain	
			information to be exchanged	
121	CALS		Is an attempt to integrate text, graphics and	
			image data into standard document architecture	
	Output			
122	Primitives in		Polyline, Polymakers, Text and Fill area	
	GKS			
123	IGES Problem		Export choices	
	1020 11001011		Tolerances, accuracy and resolution	
124	GKS-3D		Display of 3D graphical primitives	
			Mechanisms to obtain 3D input	
125	GKS Cell Array		Array function displays raster like images in a	
			device- independent manner	
			Placement Questions	
			A. 22	
	How many times		B. 24	
	are the hands of		C. 44	
126			D. 48	
	a clock at right		Explanation:	
	angle in a day?		In 12 hours, they are at right angles 22 times.	
			·· In 24 hours, they are at right angles 44 times.	
			A.10.8	
	A train moves		B.18	
127	with a speed of		C.30	
	108 kmph. Its			
	speed in metres		D.38.8	
	per second is:	_	Explanation: $108 \text{ kmph} = 108*[5/18] \text{ m/sec} = 30$	
	-		m/s.	
	Determine the		Collectivity and Telline	
	probability that a		Total no. of Digits = 12. Equally likely cases =	
100	digit chosen at		12.	
128	random from the		There are six odd digits. Probability = $6 / 12 = 1$	
	digits 1, 2, 3,		/2	
	12 will be			
	odd.			
	In covering a			
	distance of 40			
	km, Kamlesh		A. 11 kmph	
	takes 2 hours		B. 5 kmph	
	more than			
	Pankaj. If		C. 9 kmph	
100	Kamlesh doubles		D. 6 kmph	
129	his speed, then		Answer:B	
	he would take 1		Explanation: Let Kamlesh's speed be x km/hr.	
	hour less than		Then, $\frac{40}{x} - \frac{40}{(2x)} = 4$	
	Pankaj. Then		8x = 40	
	what is		x = 5 km/hr	
	Kamlesh's			
	speed?			
-	Solve the		A 50	
130			A. 58	
	equation		B. 48	

	x+34=82	C. 55
	X+34-62	D. 60
	<u> </u>	Explanation: x=82-34=48
	An accurate	
	clock shows 8	A.360.
	o'clock in the	B.180
	morning.	C.90
	Through how	D.60
131	may degrees will	Answer: B) 180
	the hour hand	Explanation:
	rotate when the	
	clock shows 2	Angle traced by the hour hand in 6
	o'clock in the	hours=(360/12)*6
	afternoon?	
	Excluding	
	stoppages, the	
	speed of a bus is	A. 9
	54 kmph and	B. 10
	including	C. 12
132	stoppages, it is	D. 20
102	45 kmph. For	Explanation:
	how many	Due to stoppages, it covers 9 km less.
	minutes does the	Time taken to cover 9 km = $\frac{9}{54}$ x 60min = 10 min
		Time taken to cover $\frac{3}{5}$ km = $\frac{10}{54}$ mm = 10 mm
	bus stop per hour?	
	Find the no.,	
	when 15 is	to Table Table 1
100	subtracted from	Let the number be x.
133	7 times the no.,	$7x - 15 = 2x + 10 \Rightarrow 5x = 25 \Rightarrow x = 5$
	the result is 10	
	more than twice	
	of the number	
		A.1.12
	If 0.75: x :: 5:8,	B.1.16
134	then x is equal	C.1.20
104	to:	D.1.30
		Explanation: $(x * 5) = (0.75 * 8)$
	_	 X=6/5=1.20
		A. Tuesday
		B. Monday
	Today is	C. Sunday
	_	D. Saturday
135	Monday. After	Answer: D) Saturday
	61 days, it will	Explanation: Each day of the week is repeated
	be:	after 7 days. So, after 63 days, it will be
		Monday.
		After 61 days, it will be Saturday.
	Adam can do a	Adam can do 1/15 of the job per day
	job in 15 days;	Eve can do 1/20 of the job per day
136	Eve can do the	If they work together they can do 7/60 of the
	same job in 20	work together they can do 7/80 of the
	541110 JOU 111 20	" of together

	1 70.4	B 11 114 8/20 20/20 20/2	
	days. If they	Remaining job 1 - $7/60 = 32/60 = 8/15$	
	work together		
	for 4 days, what		
	fraction of job is		
	incomplete?		
		A.31	
	Which one of the	B. 61	
137	following is not	C. 71	
	a prime number?	D. 91	
		Explanation:	
		91 is divisible by 7. So, it is not a prime number	•
		A. 7	
		B. 9	
1.00	Find c, if 5c - 2	C. 11	
138	= 33	D. 13	
		Explanation:	
		We add 2 to both sides and get $5c-2+2=33+2$, or	
		5c=35. We divide both sides by 5 to get c=7.	
		A. 3.6	
	A person crosses	B. 7.2	
	a 600 m long	C. 8.4	
139	street in 5	D. 10	
	minutes. What is		
	his speed in km	Explanation:	
	per hour?	Speed = $600/5 \times 60 \text{ m/sec.} = 2 \text{ m/sec.}$	
	1.0	$= 2 \times 18/5 \text{km/hr} = 7.2 \text{ km/hr}$	
	A and B can do a	The second secon	
	piece of work in		
	4 days, while C	A. D. C I.D. 'III	
140	and D can do the	A, B, C and D will together take $\frac{1}{4} + \frac{1}{12} = \frac{4}{1}$	2
140	same work in 12	= 1/3.	
	days. In how	3 days to complete the work.	
	many days will	7.46.7	
	A, B, C and D do		
	it together?	Λ 25	
	The average of	A.25 B.35	
	five numbers is	C.45	
	27. If one	D.55	
141	number is	Answer:B	
141	excluded, the	Explanation:	
	average becomes	(27*5)-(25*4)	
	25. The excluded	135-100	
	number is?	35	
		A.4	
		B.8	
	The maximum	C.2	
142	gap between two	D.1	
174	successive leap	Answer: B) 8	
	year is?	Explanation: This can be illustrated with an	
		example. Ex: 1896 is a leap year. The next leap	
		champic. Ex. 1030 is a icap year. The next leap	

			year comes in 1904 (1900 is not a leap year).
	A guy bought 10		A. 10%
	pencils for Rs.		B. 5%
144	50 and sold them		C. 20%
	for Rs. 60. What		D. 12%
	is his gain in		Answer:C
	terms of		Explanation:
	percentage?		`"Gain%"=("Gain"/"C.P")*100=20%`
	Two trains		Gaiii / C.1) 100–20/0
	starting at the		
	same time from		
	2 stations 200		
	km apart and		In the same time, they cover 110 km and 90 km
	going in opposite		respectively.
145	direction cross		For the same time, speed and distance is
143	each other at a		inversely proportional.
	distance of 110		So ratio of their speed = 110:90 = 11: 9
	km from one of		So ratio of their speed = 110.90 = 11.9
	the stations.		- Table 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1
	What is the ratio		
	of their speeds?		
	In 100 m race, A		A. 20m
	covers the		B. 25m
	distance in 36		C. 22.5m
146	seconds and B in		D. 9m
110	45 seconds. In		Explanation:
	this race A beats		Distance covered by B in 9 sec. = (100/45)*9m
	B by:		= 20 m
			A.0.2
			B.0.02
		_	C.0.005
	Half percent,		D.0.05
147	written as a		Answer: C
	decimal, is		
			Explanation:
			As we know, $1\% = 1/100$
			Hence, $(1/2)\% = (1/2 * 1/100) = 1/200 = 0.005$
	A pump can fill		4 10 10 10 10 10
	a tank with water		A. 4 1/3 Hours
	in 2 hours.		B. 7 Hours
	Because of a		C. 8 Hours
148	leak, it took 2.5		D. 10 Hours
	hours to fill the		Explanation:
	tank. The leak		Work done by the leak in 1 hour = $\begin{pmatrix} 1 & 2 \\ 2 & 5 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 10 & 1 \end{pmatrix}$
	can drain all the		,
	water of the tank		: Leak will empty the tank in 10 hrs.
	in:		
	If a number is		We have 1,8,27 and 64 as perfect cubes from 1
149	chosen at		to 100.
11/	random from 1		Thus, the probability of picking a perfect cube is
	to 100, then the	U. Caracian de la Car	4/100 = 1/25

	probability that the chosen number is a perfect cube is		
150	Three times the first of three consecutive odd integers is 3 more than twice the third. The third integer is:	 A. 9 B. 11 C. 13 D. 15 Explanation: Let the three integers be x , $x + 2$ and $x + 4$. Then, $3x = 2(x + 4) + 3 \Leftrightarrow x = 11$. \therefore Third integer $= x + 4 = 15$.	

